DATA SHEET

TDA8580J
Multi-purpose power amplifier

Preliminary specification
Supersedes data of 1998 Feb 25
File under Integrated Circuits, IC01

2000 Apr 18

Philips
Semiconductors

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FEATURES

General

- Supply voltage range from 8 to 24 V
- Low distortion
- Few external components, fixed gain
- High output power
- Can be used as a stereo amplifier in Bridge-Tied Load (BTL) or quad Single-Ended (SE) amplifiers
- Single-ended mode without loudspeaker capacitor
- Mute and standby mode with one- or two-pin operation
- Diagnostic information for Dynamic Distortion Detector (DDD), high temperature (145 °C) and short-circuit
- No switch on/off plops when switching between standby and mute or mute and on; an external RC-network is prescribed to ensure plop-free operation
- Low offset variation at outputs between mute and on
- Fast mute on supply voltage drops.

Protection

- Short-circuit proof to ground, positive supply voltage and across load; the supply voltage ranges where the different short circuit conditions are guaranteed are given in Chapter “Limiting values”
- ESD protected on all pins
- Thermal protection against temperatures exceeding 150 °C.

GENERAL DESCRIPTION

The TDA8580J is a stereo Bridge-Tied Load (BTL) or a quad Single-Ended (SE) amplifier that operates over a wide supply voltage range from 8 to 24 V. This makes it suitable for applications such as television, home-sound systems and active speakers.

Because of an internal voltage buffer, this device can be used without a capacitor connected in series with the load (SE application). A combined BTL and 2 × SE application can also be configured (one chip stereo and subwoofer application).

ORDERING INFORMATION

TYPE NUMBER	PACKAGE		
	NAME	DESCRIPTION	VERSION
TDA8580J	DBS17P	plastic DIL-bent-SIL power package; 17 leads (lead length 12 mm)	SOT243-1

QUICK REFERENCE DATA

SYMBOL	PARAMETER	CONDITIONS	MIN.	TYP.	MAX.	UNIT
V_P	operating supply voltage		8.0	14.4	24	V
$I_{q(tot)}$	total quiescent current	V_P = 14.4 V	–	140	170	mA
I_{stb}	standby supply current	V_P = 14.4 V	–	1	50	µA
Bridge-tied load application						
G_v	voltage gain		31	32	33	dB
P_o	output power	THD = 0.5%; V_P = 14.4 V; R_L = 4 Ω	14	15	–	W
		THD = 0.5%; V_P = 24 V; R_L = 8 Ω	21	23	–	W
THD	total harmonic distortion	f_i = 1 kHz; P_o = 1 W; V_P = 14.4 V; R_L = 4 Ω	–	0.05	0.1	%
		f_i = 1 kHz; P_o = 10 W; V_P = 24 V; R_L = 8 Ω	–	0.02	0.05	%
$V_{offset(DC)}$	DC output offset voltage	V_P = 14.4 V; mute condition; R_L = 4 Ω	–	10	20	mV
		V_P = 14.4 V; on condition	–	0	140	mV
V_{no}	noise output voltage	R_S = 1 kΩ; V_P = 14.4 V	–	100	150	µV
SVRR	supply voltage ripple rejection	f_i = 1 kHz; $V_{ripple(p-p)}$ = 2 V; on or mute condition; R_S = 0 Ω	50	60	–	dB
Single-ended application						
G_v	voltage gain		25	26	27	dB
P_o	output power	THD = 0.5%; V_P = 14.4 V; R_L = 4 Ω	3.8	4.0	–	W
		THD = 0.5%; V_P = 24 V; R_L = 4 Ω	10.5	11.5	–	W
$V_{offset(DC)}$	DC output offset voltage	V_P = 14.4 V; mute condition; R_L = 4 Ω	–	10	20	mV
		V_P = 14.4 V; on condition	–	0	100	mV
V_{no}	noise output voltage	R_S = 1 kΩ; V_P = 14.4 V	–	80	120	µV
SVRR	supply voltage ripple rejection	f_i = 1 kHz; $V_{ripple(p-p)}$ = 2 V; on or mute condition; R_S = 0 Ω	40	45	–	dB

BLOCK DIAGRAM

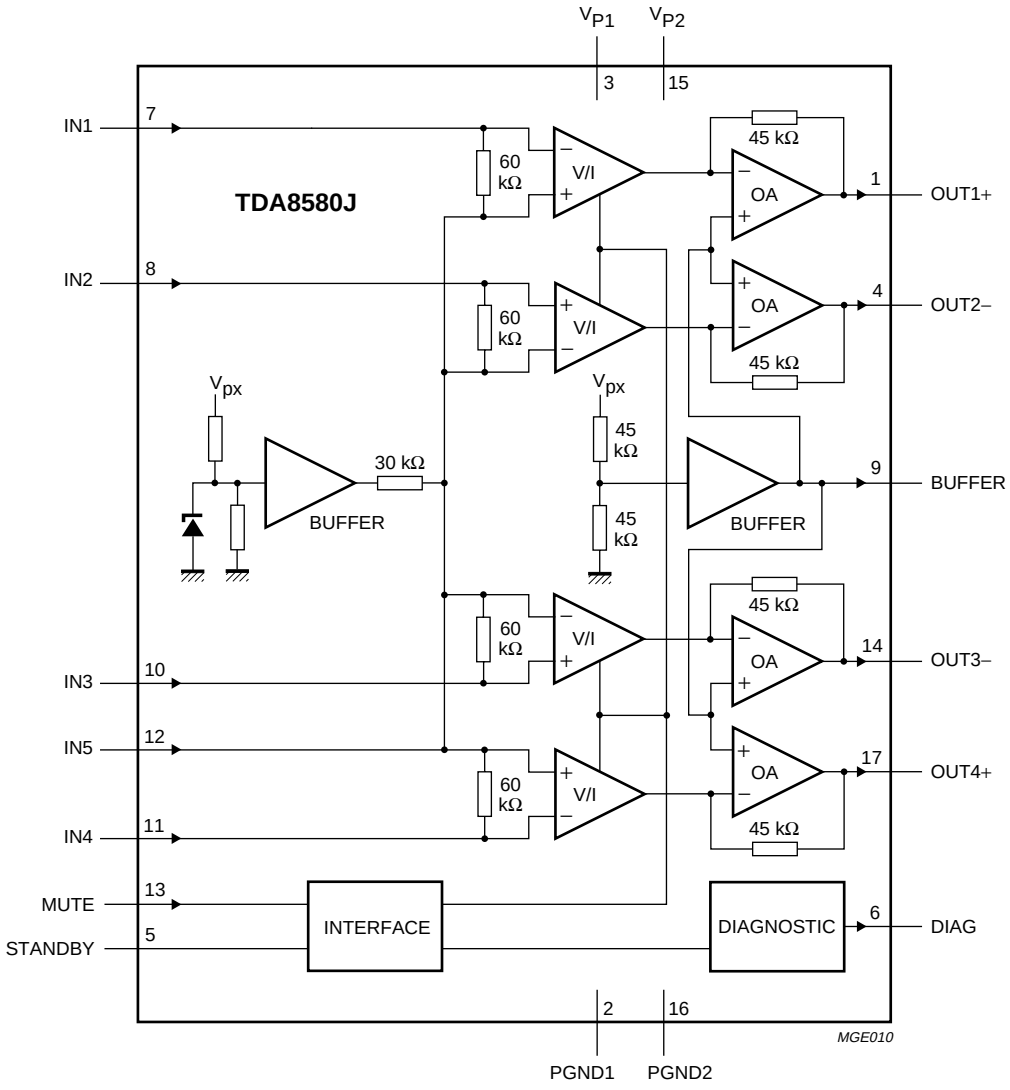


Fig.1 Block diagram.

PINNING

SYMBOL	PIN	DESCRIPTION
OUT1+	1	non-inverting output 1
PGND1	2	power ground 1
V_{P1}	3	supply voltage 1
OUT2–	4	inverting output 2
STANDBY	5	standby/mute/on selection input
DIAG	6	diagnostic output
IN1	7	input 1
IN2	8	input 2
BUFFER	9	single-ended buffer output
IN3	10	input 3
IN4	11	input 4
IN5	12	input 5; signal ground capacitor connection
MUTE	13	mute/on selection input
OUT3–	14	inverting output 3
V_{P2}	15	supply voltage 2
PGND2	16	power ground 2
OUT4+	17	non-inverting output 4

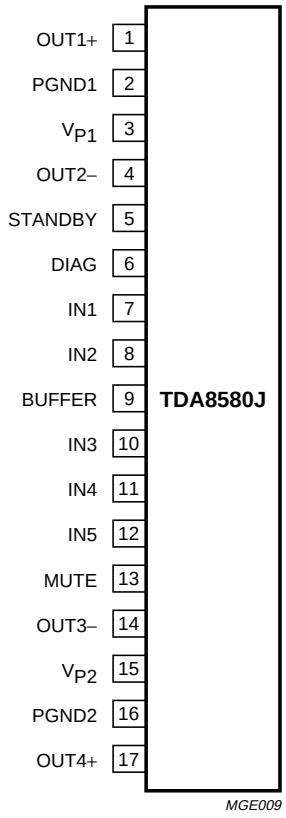


Fig.2 Pin configuration.

FUNCTIONAL DESCRIPTION

The TDA8580J is a multi-purpose power amplifier with four amplifiers which can be connected in the following configurations with high output power and low distortion (at minimum quiescent current):

- Dual bridge-tied load amplifiers
- Quad single-ended amplifiers
- Dual single-ended amplifiers and one bridge-tied load amplifier.

The amplifier can be switched in on, mute and off (standby) by the MUTE and STANDBY pins (for interfacing directly with a microcontroller). One-pin operation is also possible by applying a voltage greater than 8 V to the STANDBY pin to switch the amplifier in on mode.

Special attention is given to the dynamic behaviour as follows:

- Slow offset change between mute and on (controlled by MUTE and STANDBY pins)
- Low noise levels, which are independent of the supply voltage.

Protections are included to avoid the IC being damaged at:

- Over temperature: T_j > 150 °C
- Short-circuit of the output pin(s) to ground or supply rail; when short-circuited, the power dissipation is limited
- ESD protection (Human Body Model 3000 V, Machine Model 300 V)
- Energy handling. A DC voltage of 6 V can be connected to the output of any amplifier while the supply pins are short-circuited to ground.

Diagnostics are available for the following conditions (see Figs 3, 4 and 5):

- Chip temperature above 145 °C
- Distortion over 2% due to clipping
- Short-circuit protection active.

LIMITING VALUES

In accordance with the Absolute Maximum Rating System (IEC 60134).

SYMBOL	PARAMETER	CONDITIONS	MIN.	MAX.	UNIT
V_P	supply voltage	operating	–	24	V
		no signal condition	–	28	V
V_{DIAG}	voltage on pin DIAG		–	18	V
I_{OSM}	non-repetitive peak output current		–	6	A
I_{ORM}	repetitive peak output current		–	4.5	A
$V_{P(scol)}$	supply voltage with short-circuit across load		–	28	V
$V_{P(scg)}$	supply voltage with short-circuit from output to ground		–	26	V
$V_{P(scs)}$	supply voltage with short-circuit from output to supply		–	16	V
$V_{P(rp)}$	reverse polarity		–	6	V
P_{tot}	total power dissipation		–	75	W
T_j	junction temperature		–	150	°C
T_{stg}	storage temperature		–55	+150	°C
T_{amb}	ambient temperature		–40	+85	°C

THERMAL CHARACTERISTICS

SYMBOL	PARAMETER	CONDITIONS	VALUE	UNIT
$R_{th(j-a)}$	thermal resistance from junction to ambient	in free air	40	K/W
$R_{th(j-c)}$	thermal resistance from junction to case		1.5	K/W

CHARACTERISTICS

V_P = 14.4 V; T_{amb} = 25 °C; f_i = 1 kHz; R_L = ∞; measured in test circuit of Fig.28; unless otherwise specified.

SYMBOL	PARAMETER	CONDITIONS	MIN.	TYP.	MAX.	UNIT
Supplies						
V_P	operating supply voltage		8.0	14.4	24	V
$I_{q(tot)}$	total quiescent current		–	140	170	mA
I_{stb}	standby current		–	1	50	µA
V_O	DC output voltage		–	7.0	–	V
$V_{P(mute)}$	low supply voltage mute		6.0	7.0	8.0	V
V_I	DC input voltage		–	4.0	–	V
Control pins						
STANDBY PIN (see Table 1)						
$V_{5(stb)}$	voltage at STANDBY pin for standby condition		0	–	0.8	V
$V_{hys(5)(stb)}$	hysteresis voltage at STANDBY pin for standby condition	note 1	–	0.2	–	V
$V_{5(mute)}$	voltage at STANDBY pin for mute condition	V_{13} < 0.8 V	2.0	–	5.3	V
$V_{5(on)}$	voltage at STANDBY pin for on condition	V_P > 9 V; note 2	8.0	–	18	V
MUTE PIN (see Table 1)						
$V_{13(mute)}$	voltage at MUTE pin for mute condition	V_5 = 5 V	0	–	0.8	V
$V_{13(on)}$	voltage at MUTE pin for on condition	V_5 = 5 V	2.5	–	5.3	V
Diagnostic; output buffer (open-collector); see Figs 3, 4 and 5						
V_{OL}	LOW-level output voltage	I_{sink} = 1 mA	–	0.2	0.8	V
I_{LI}	leakage current	V_{DIAG} = 14.4 V	–	–	1	µA
CD	clip detector	V_{DIAG} < 0.8 V	1	2	4	%
$T_{j(diag)}$	junction temperature for high temperature warning	V_{DIAG} < 0.8 V	–	145	–	°C
Stereo BTL application; see Figs 6, 7, 10, 11, 14, 15, 18, 19, 21, 22, 23, 24, 26 and 28						
THD	total harmonic distortion	f_i = 10 kHz; P_o = 1 W; R_L = 4 Ω; filter: 22 Hz < f < 30 kHz	–	0.2	0.3	%
		f_i = 1 kHz; P_o = 1 W; V_P = 14.4 V; R_L = 4 Ω	–	0.05	0.1	%
		f_i = 1 kHz; P_o = 10 W; V_P = 24 V; R_L = 8 Ω	–	0.02	0.05	%
P_o	output power	THD = 0.5%; V_P = 14.4 V; R_L = 4 Ω	14	15	–	W
		THD = 0.5%; V_P = 24 V; R_L = 8 Ω	21	23	–	W
		THD = 10%; V_P = 14.4 V; R_L = 4 Ω	18	20	–	W
		THD = 10%; V_P = 24 V; R_L = 8 Ω	28	30	–	W
G_v	voltage gain	$V_{o(rms)}$ = 3 V	31	32	33	dB

SYMBOL	PARAMETER	CONDITIONS	MIN.	TYP.	MAX.	UNIT
α_{cs}	channel separation	P_o = 2 W; f_i = 1 kHz; R_L = 4 Ω	60	65	–	dB
$\lvert\Delta G_v\rvert$	channel unbalance		–	–	1	dB
$V_{offset(DC)}$	DC output offset voltage	on condition	–	0	140	mV
		mute condition; R_L = 4 Ω	–	10	20	mV
V_{no}	noise output voltage	R_s = 1 kΩ; V_P = 14.4 V; note 3	–	100	150	μV
$V_{no(mute)}$	noise output voltage mute	note 3	–	0	20	μV
$V_{o(mute)}$	output voltage mute	$V_{i(rms)}$ = 1 V	–	3	500	μV
SVRR	supply voltage ripple rejection	R_s = 0 Ω; f_i = 1 kHz; $V_{ripple(p-p)}$ = 2 V; on or mute condition	50	60	–	dB
Z_i	input impedance		23	30	37	kΩ
CMRR	common mode rejection ratio	R_s = 0 Ω; $V_{i(rms)}$ = 0.5 V; f_i = 1 kHz	–	60	–	dB
Quad SE application; see Figs 8**,** 9**,** 12**,** 13**,** 16**,** 17**,** 20**,** 25, 27 and 29						
THD	total harmonic distortion	f_i = 1 kHz; P_o = 1 W; R_L = 4 Ω	–	0.05	0.1	%
		f_i = 10 kHz; P_o = 1 W; R_L = 4 Ω; filter: 22 Hz < f < 30 kHz	–	0.2	0.3	%
		f_i = 1 kHz; P_o = 1 W; V_P = 24 V, R_L = 4 Ω; filter: 22 Hz < f < 30 kHz	–	0.05	0.1	%
P_o	output power	THD = 0.5%; V_P = 14.4 V; R_L = 4 Ω	3.8	4.0	–	W
		THD = 0.5%; V_P = 24 V; R_L = 4 Ω	10.5	11.5	–	W
		THD = 10%; V_P = 14.4 V; R_L = 4 Ω	4.9	5.2	–	W
		THD = 10%; V_P = 24 V; R_L = 4 Ω	14	15	–	W
G_v	voltage gain	$V_{o(rms)}$ = 3 V	25	26	27	dB
α_{cs}	channel separation	P_o = 2 W; f_i = 1 kHz; R_L = 4 Ω	40	46	–	dB
$\lvert\Delta G_v\rvert$	channel unbalance		–	–	1	dB
$V_{offset(DC)}$	DC output offset voltage	V_P = 14.4 V; on condition	–	0	100	mV
		V_P = 14.4 V; mute condition; R_L = 4 Ω	–	10	20	mV
V_{no}	noise output voltage	R_s = 1 kΩ; V_P = 14.4 V; note 3	–	80	120	μV
$V_{no(mute)}$	noise output voltage mute	note 3	–	0	20	μV
$V_{o(mute)}$	output voltage mute	$V_{i(rms)}$ = 1 V	–	3	500	μV
SVRR	supply voltage ripple rejection	f_i = 1 kHz; $V_{ripple(p-p)}$ = 2 V, on or mute condition; R_s = 0 Ω	40	45	–	dB
Z_i	input impedance		46	60	74	kΩ
CMRR	common mode rejection ratio	$V_{i(rms)}$ = 0.5 V; f_i = 1 kHz; R_s = 0 Ω	–	60	–	dB

Notes

1. Hysteresis between the rise and fall voltage when pin STANDBY is controlled with low ohmic voltage source.
2. At lower V_P the voltage at the STANDBY pin for on condition will be adjusted automatically to maintain an on condition at low battery voltage (down to 8 V) when using one-pin operation.
3. The noise output is measured in a bandwidth of 20 Hz to 20 kHz.

Table 1 Selection of standby, mute and on

VOLTAGE AT PIN STANDBY	VOLTAGE AT PIN MUTE	FUNCTION
< 0.8 V	don't care	standby (off)
2 to 5.3 V	< 0.8 V	mute (DC settled)
2 to 5.3 V	2.5 to 5.3 V	on (AC operating)
≥ 8.0 V	don't care	on (AC operating)

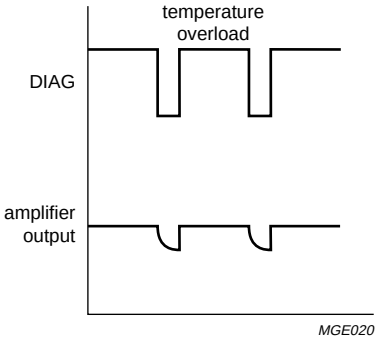


Fig.3 Diagnostic waveform: temperature overload.

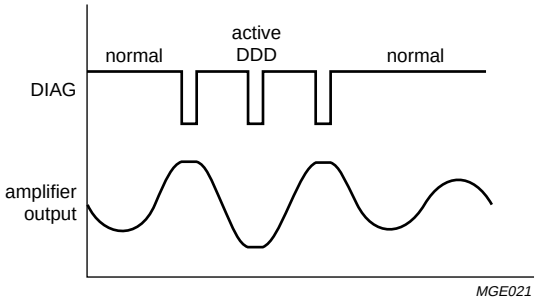


Fig.4 Diagnostic waveform: DDD function.

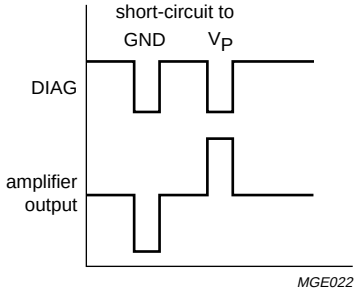
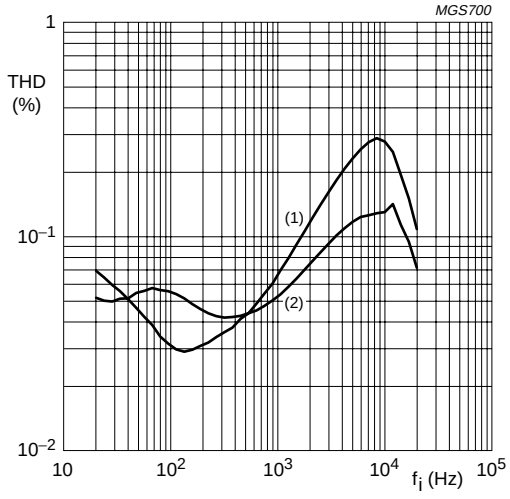
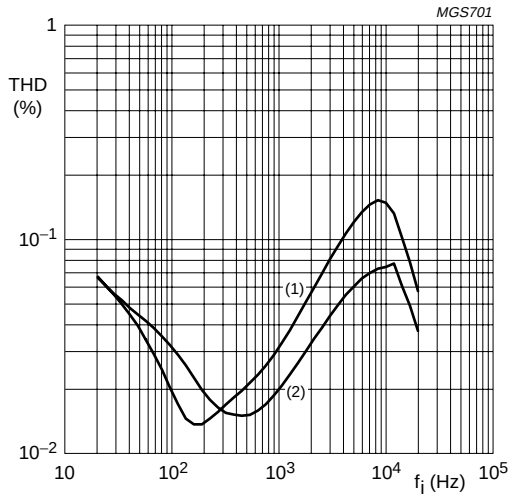


Fig.5 Diagnostic waveform: short-circuit to GND or V_P.



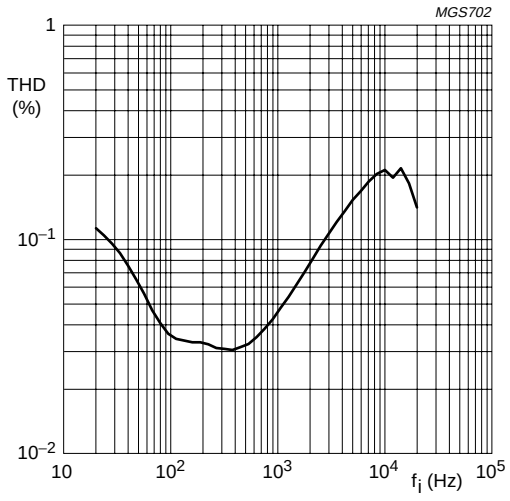
R_L = 4 Ω; V_P = 14.4 V; 2 channel driven.
(1) P_o = 1 W.
(2) P_o = 10 W.

Fig.6 Total harmonic distortion as a function of frequency; BTL mode.



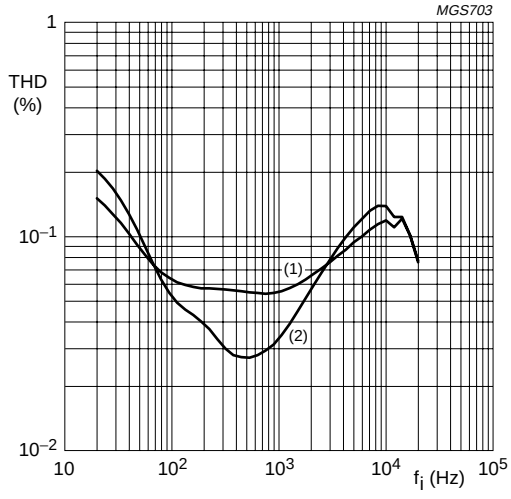
R_L = 8 Ω; V_P = 24 V; 2 channel driven.
(1) P_o = 1 W.
(2) P_o = 10 W.

Fig.7 Total harmonic distortion as a function of frequency; BTL mode.



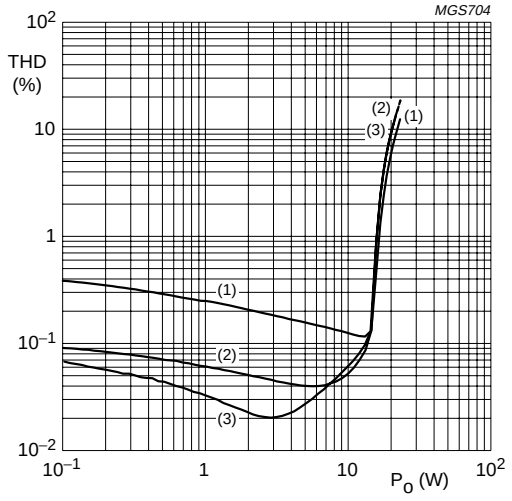
P_o = 1 W; R_L = 4 Ω; V_P = 14.4 V; 4 channel driven.

Fig.8 Total harmonic distortion as a function of frequency; SE mode.



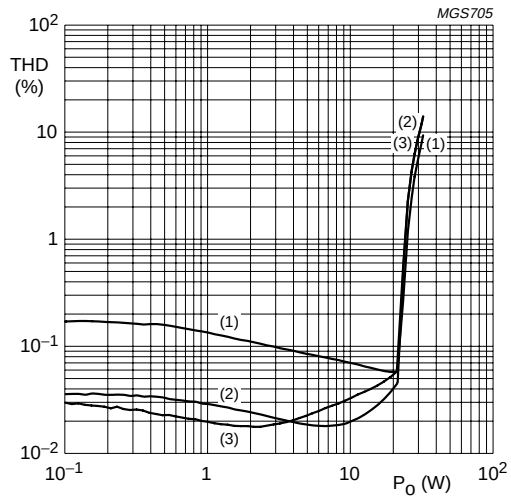
R_L = 4 Ω; V_P = 24 V; 4 channel driven.
(1) P_o = 5 W.
(2) P_o = 1 W.

Fig.9 Total harmonic distortion as a function of frequency; SE mode.



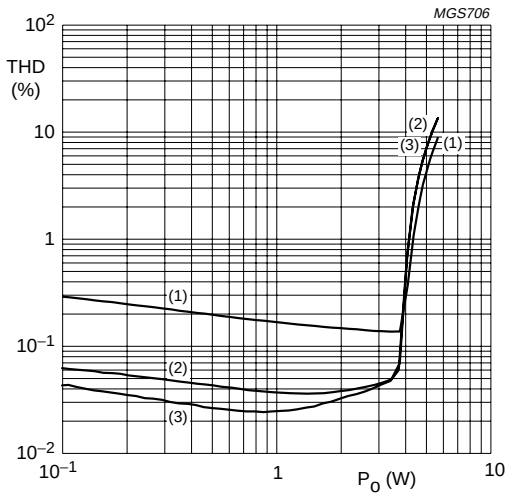
R_L = 4 Ω; V_P = 14.4 V; 2 channel driven.
(1) f_i = 10 kHz.
(2) f_i = 1 kHz.
(3) f_i = 100 Hz.

Fig.10 Total harmonic distortion as a function of output power; BTL mode.



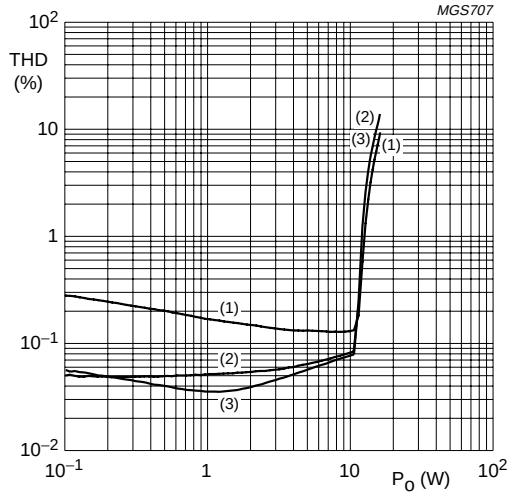
R_L = 8 Ω; V_P = 24 V; 2 channel driven.
(1) f_i = 10 kHz.
(2) f_i = 1 kHz.
(3) f_i = 100 Hz.

Fig.11 Total harmonic distortion as a function of output power; BTL mode.



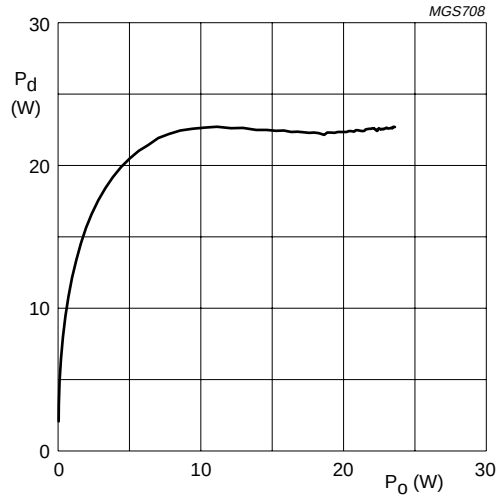
R_L = 4 Ω; V_P = 14.4 V; 4 channel driven
(1) f_i = 10 kHz.
(2) f_i = 1 kHz.
(3) f_i = 100 Hz.

Fig.12 Total harmonic distortion as a function of output power; SE mode.



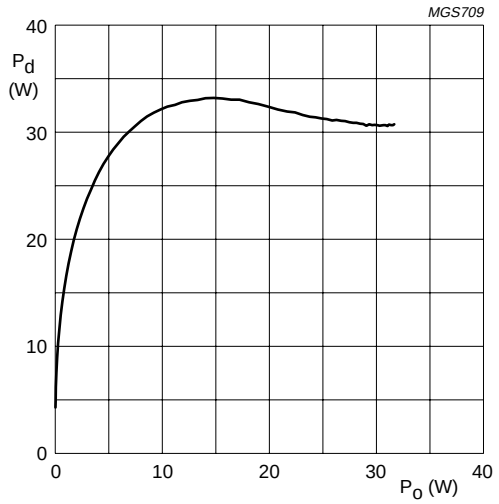
R_L = 4 Ω; V_P = 24 V; 4 channel driven.
(1) f_i = 10 kHz.
(2) f_i = 1 kHz.
(3) f_i = 100 Hz.

Fig.13 Total harmonic distortion as a function of output power; SE mode.



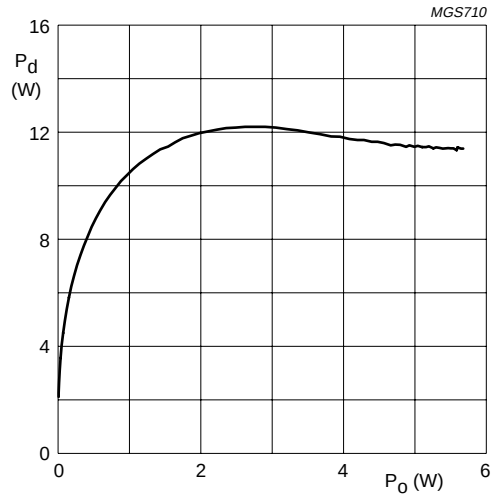
f_i = 1 kHz; R_L = 4 Ω; V_P = 14.4 V; 2 channel driven.

Fig.14 Power dissipation as a function of output power; BTL mode.



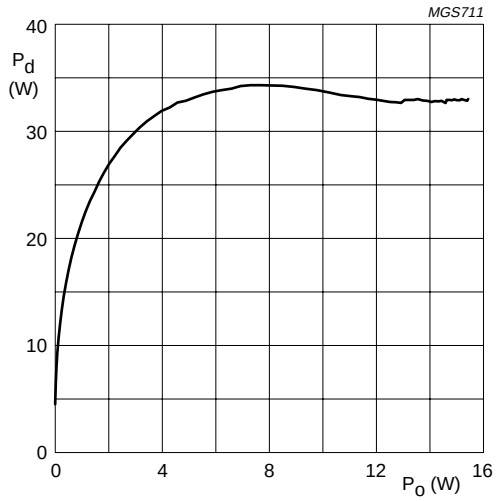
f_i = 1 kHz; R_L = 8 Ω; V_P = 24 V; 2 channel driven.

Fig.15 Power dissipation as a function of output power; BTL mode.



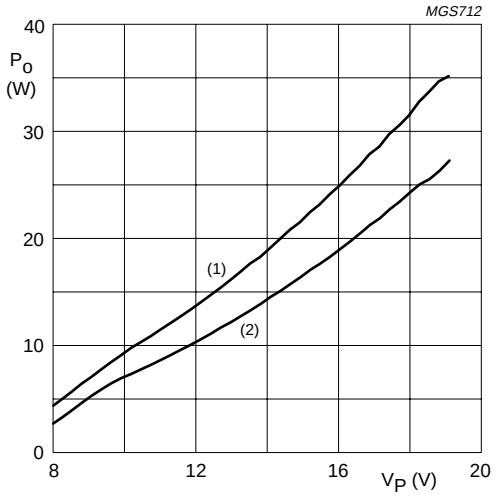
f_i = 1 kHz; R_L = 4 Ω; V_P = 14.4 V; 4 channel driven.

Fig.16 Power dissipation as a function of output power; SE mode.



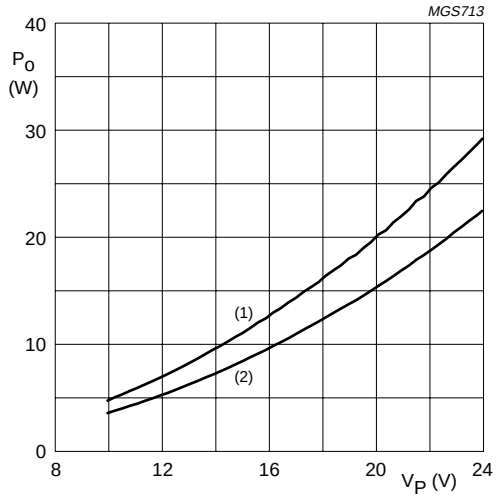
f_i = 1 kHz; R_L = 4 Ω; V_P = 24 V; 4 channel driven.

Fig.17 Power dissipation as a function of output power; SE mode.



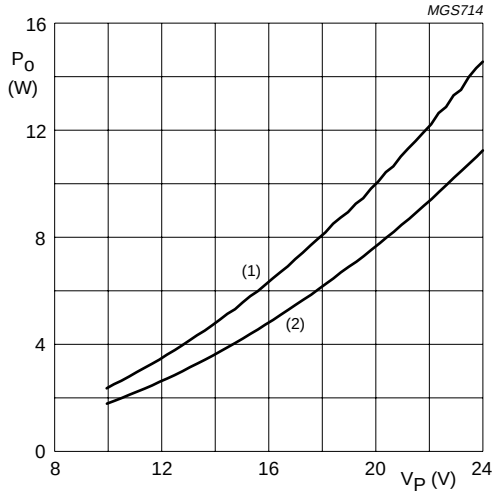
f_i = 1 kHz; R_L = 4 Ω; 2 channel driven.
(1) THD = 10%.
(2) THD = 0.5%.

Fig.18 Output power as a function of supply voltage; BTL mode.



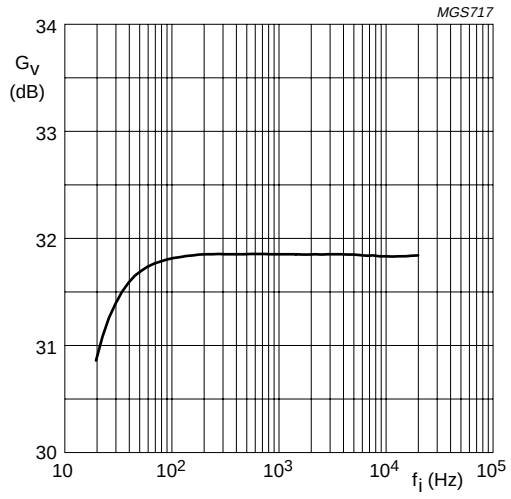
f_i = 1 kHz; R_L = 8 Ω; 2 channel driven.
(1) THD = 10%.
(2) THD = 0.5%

Fig.19 Output power as a function of supply voltage; BTL mode.



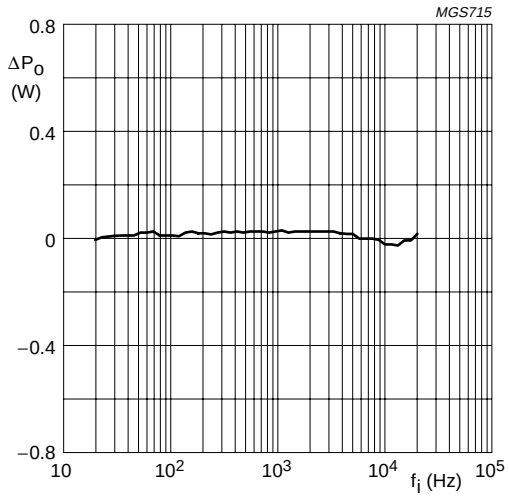
f_i = 1 kHz; R_L = 4 Ω; 2 channel driven.
(1) THD = 0.5%.
(2) THD = 10%

Fig.20 Output power as a function of supply voltage; SE mode.



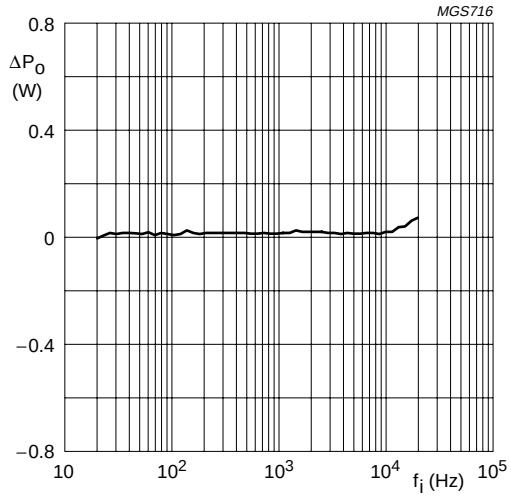
C_i = 470 nF.

Fig.21 Gain as a function of input frequency; BTL mode.



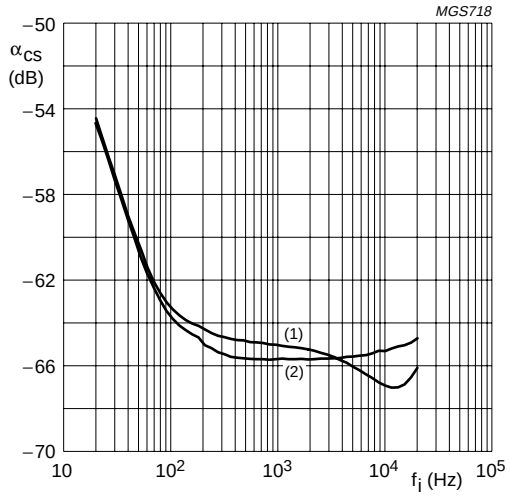
THD = 0.5%; R_L = 4 Ω; V_P = 14.4 V.

Fig.22 Power bandwidth as a function of frequency; BTL mode.



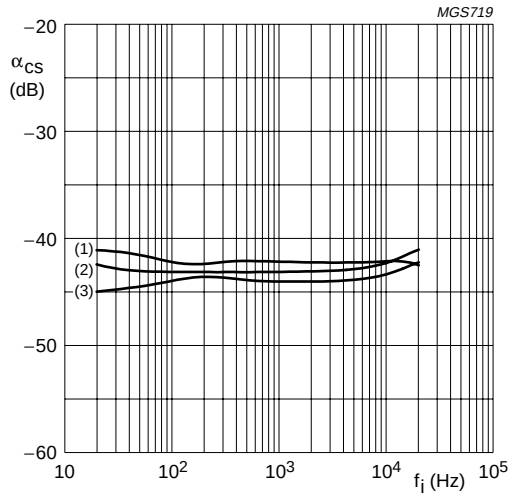
THD = 0.5%; R_L = 8 Ω; V_P = 24 V.

Fig.23 Power bandwidth as a function of frequency; BTL mode.



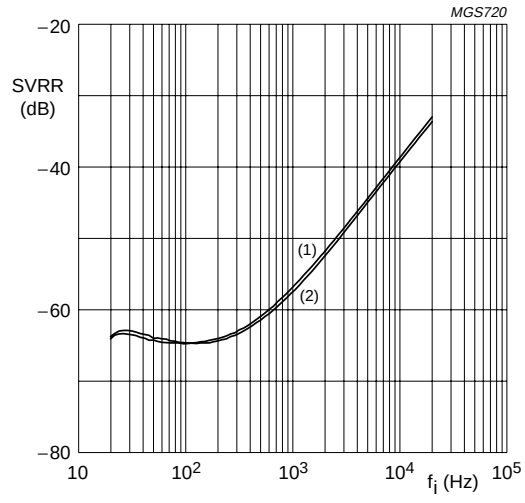
P_o = 2 W; R_L = 4 Ω; V_P = 14.4 V.
(1) Channels 3 and 4 to channels 1 and 2.
(2) Channels 1 and 2 to channels 3 and 4.

Fig.24 Channel separation as a function of frequency; BTL mode.



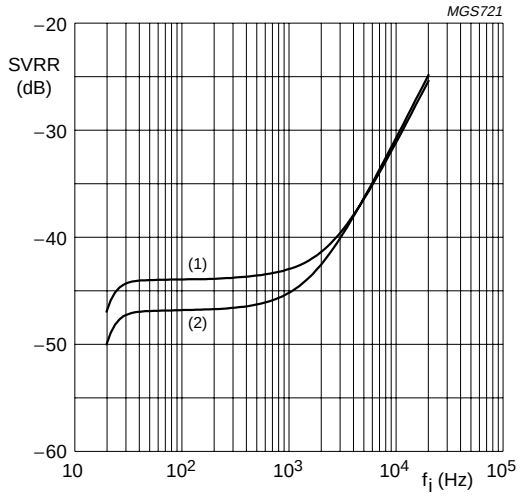
P_o = 2 W; R_S = 0 Ω; R_L = 4 Ω; V_P = 14.4 V.
(1) Channel 1 to channel 2.
(2) Channel 1 to channel 3.
(3) Channel 1 to channel 4.

Fig.25 Channel separation as a function of frequency; SE mode.



R_s = 0 Ω; $V_{ripple(p-p)}$ = 2 V.
(1) V_p = 14.4 V.
(2) V_p = 24 V.

Fig.26 SVRR as a function of frequency; BTL mode.



R_s = 0 Ω; $V_{ripple(p-p)}$ = 2 V.
(1) V_p = 14.4 V.
(2) V_p = 24 V.

Fig.27 SVRR as a function of frequency; SE mode.

APPLICATION INFORMATION

The application circuit depends on the supply voltage used. For supply voltages below 18 V the application circuits are shown in Figs 28, 29 and 30.

The typical application circuits for the different supply voltage ranges are shown in Figs 31, 32 and 33.

Additional information for the applications shown in Figs 28, 29 and 30

The RC-network connected to pin 5 determines the amplifier switch on/off behaviour as follows;

- Switched from STANDBY to MUTE when $V_{switching}$ (typically 9 V) is enabled and the switch SW1 is closed. During MUTE there is no output noise and no offset.
- Switched from MUTE to ON when the switch SW1 is opened. During switching ON the offset and noise are gradually built up. The time constant is fixed by $R1 \times C1$.

The inputs can be tied together and connected to one input capacitor. Because the input resistance is decreased by a factor of 2, the low frequency roll-off is shifted to a higher frequency when C_i is kept the same value.

The low frequency cut-off is determined by;

$$f_{-3dB} = 1/(2\pi \times R_i \times C_i)$$

$$= \frac{1}{2\pi \times 60 \times 10^{3} \times 220 \times 10^{-9}} = 12 \text{ Hz.}$$

The Boucherot network connected to the buffer (pin 9) is necessary to guarantee a low output resistance at high frequencies when the buffer is loaded (only in SE applications).

Additional information for the applications shown in Figs 31, 32 and 33

Short circuit behaviour at high supply voltages (V_p > 18 V):

- When V_p > 18 V it is advisable to use the applications given in Figs 32 and 33. In these applications the diagnostics output is tied to pin 5 (one pin operation) or pin 13 (two pin operation). During a fault condition the amplifier is soft-muted and the amplitude of the output signal is reduced at:
  - over temperature (still large dynamic range)
  - short to ground and over load (output current reduced)
- The 4.7 μF capacitor and the 10 kΩ resistor connected to pin 5 or to pin 13 are used to:
  - provide a stable loop
  - control the switch on/off behaviour
  - minimize the effect due to clip detection.

Use of common buffer

In SE applications the buffer output is used in place of a SE capacitor. To minimize the crosstalk (high channel separation) and distortion it is advised to connect the speaker wires as closely as possible to pin 9 without using a shared wire. Internally in the IC all the efforts have been taken to minimize the crosstalk by locating the feedback loops as close as possible to pin 9.

If a common wire is shared by all the speakers, the series resistance of this shared wire will introduce added signal voltages resulting from the currents flowing through this wire when a connected amplifier is driven by a signal.

Optimize the THD performance

The TDA8580J application can be optimized to gain the lowest THD possible by applying the following guidelines:

- SE application: minimize the shared wires to pin 9 (see section “Use of common buffer”).
- Because the inputs are quasi differential, ground loops can be avoided by connecting the negative terminal of the 100 μF signal ground capacitor (connected to pin 12) to the ground pin of the signal processor.

  Note: do not leave the inputs in the open condition to prevent HF oscillation.
- Increase the value of electrolytic supply capacitor (typical value 1000 μF) to the maximum possible to minimize cross talk and distortion at low signal frequencies, due to the PSRR (power supply rejection ratio). For suppressing high frequency transients on the supply line a capacitor (typical value 100 nF) with a low ESR is required to be connected in parallel with the electrolytic capacitor. The capacitor combination must be placed as close as possible to the IC (using short interconnection tracks).

Headroom

A typical CD requires at least 12 dB dynamic headroom (a factor of 15.85), compared with the average power output, for passing the loudest parts without distortion.

For BTL application at V_p = 24 V, R_L = 8 Ω and P_o at THD = 0.5% (see Fig.15), the Average Listening Level (ALL) for music power without distortion yields:

$$P_{o(ALL)} = \frac{23}{15.85} = 1.45 \text{ W}.$$

Table 2 P_d as a function of headroom (music signals) for $P_o = 2 \times 23$ W (THD = 0.5%).

HEADROOM	P_d
0 dB	32 W
12 dB	16 W

So for the average music listening level a total power dissipation of 16 W can be used for calculating the optimum heat sink thermal resistance.

Heatsink calculation

The measured thermal resistance of this package $R_{th(j-c)}$ is a maximum of 1.5 K/W. For a maximum ambient temperature of 60°C the required heatsink thermal resistance can be calculated as shown in the following example.

EXAMPLE

Measured or given values:

V_p = 24 V

R_L = 8 Ω (2 × BTL)

Measured worst case P_d (sine wave) = 32 W

$T_{j(max)}$ = 150°C

$T_{amb(max)}$ = 60°C

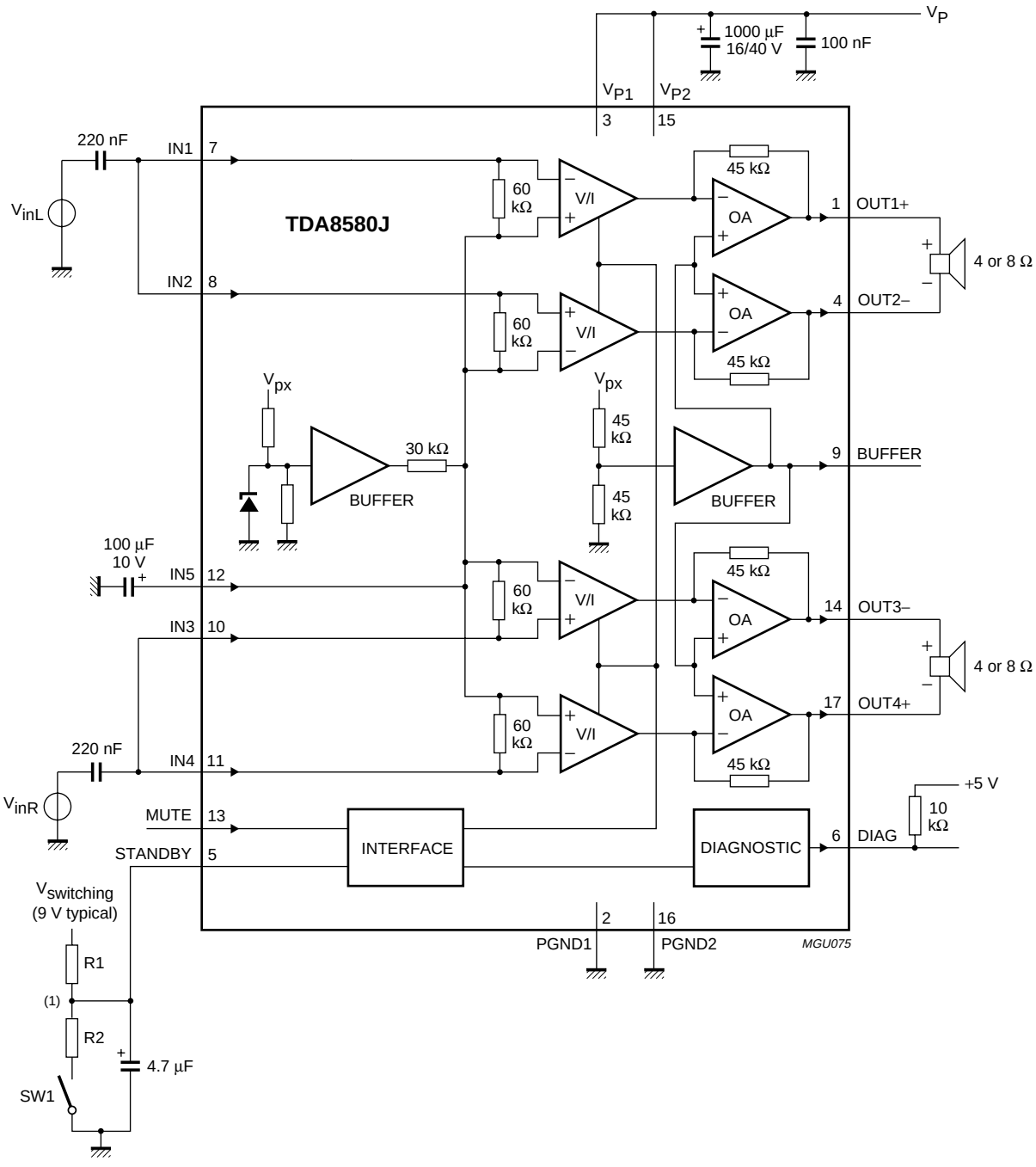
$R_{th(j-c)}$ = 1.5 K/W

$$R_{th(hs)} = \frac{T_{j(max)} - T_{amb(max)}}{P_d} - R_{th(j-c)}$$

$$= \frac{150 - 60}{32} - 1.5 = 1.3 \text{ K/W}$$

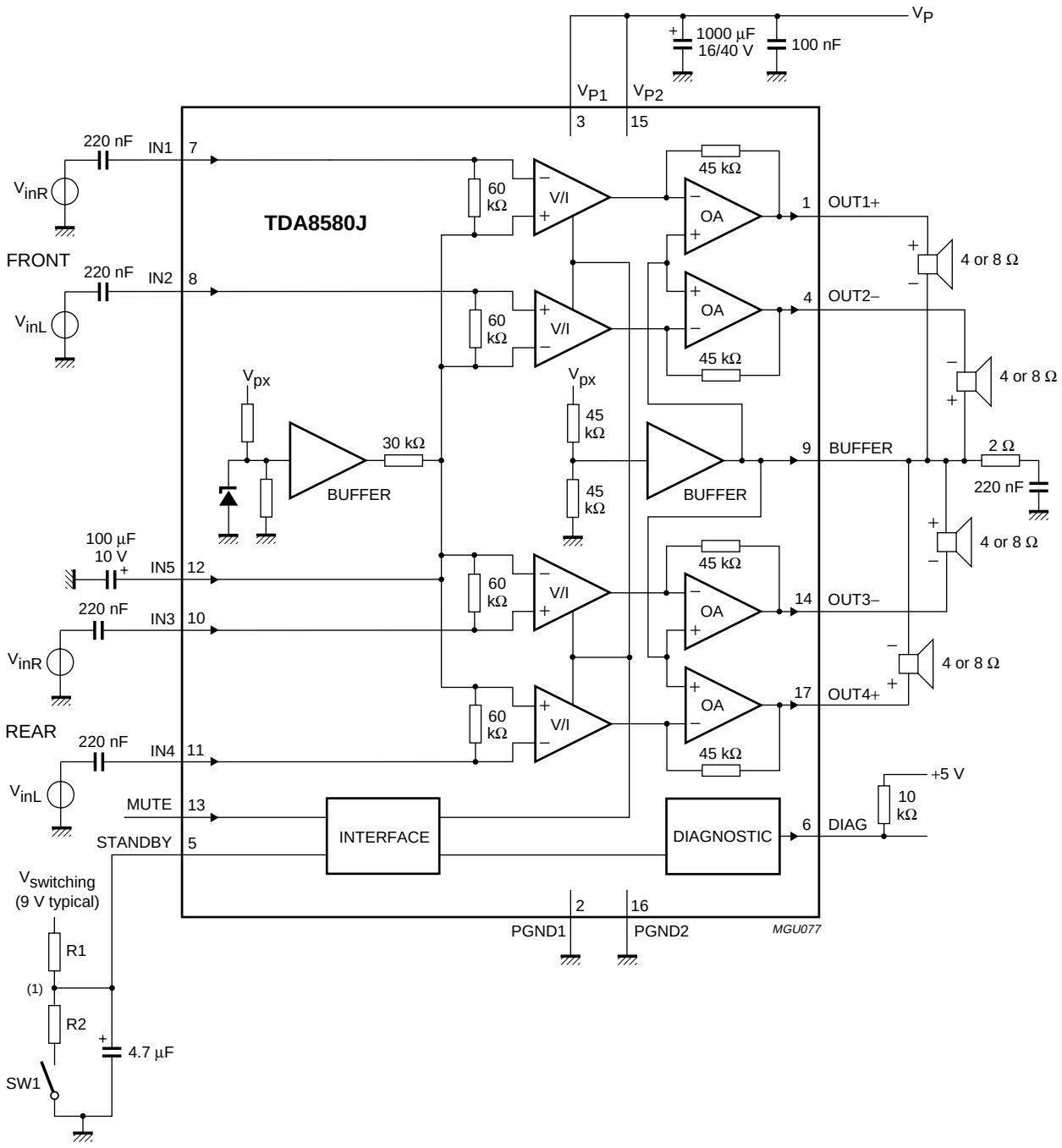
Table 3 Heatsink thermal resistance as a function of headroom for $P_o = 2 \times 23$ W (THD = 0.5%).

HEAD ROOM	P_d	$R_{th(hs)}$
0 dB	32 W	1.3 K/W
12 dB	16 W	4.12 K/W



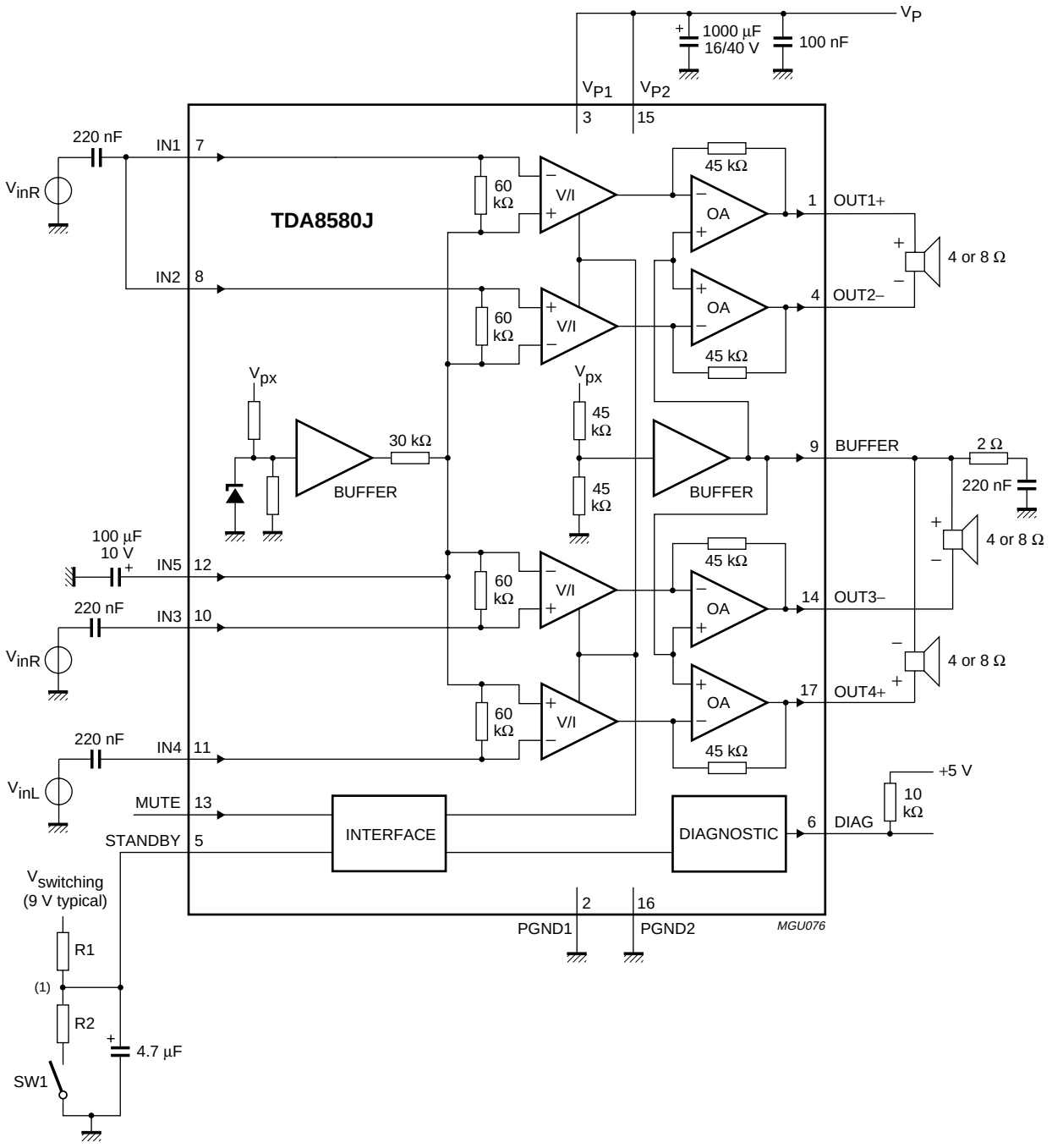
(1) R1 and R2 values depend on $V_{switching}$ applied; the value of R1 and R2 connected in parallel should be minimum 10 kΩ.

Fig.28 Stereo bridge-tied load application; $V_P \leq 18$ V.



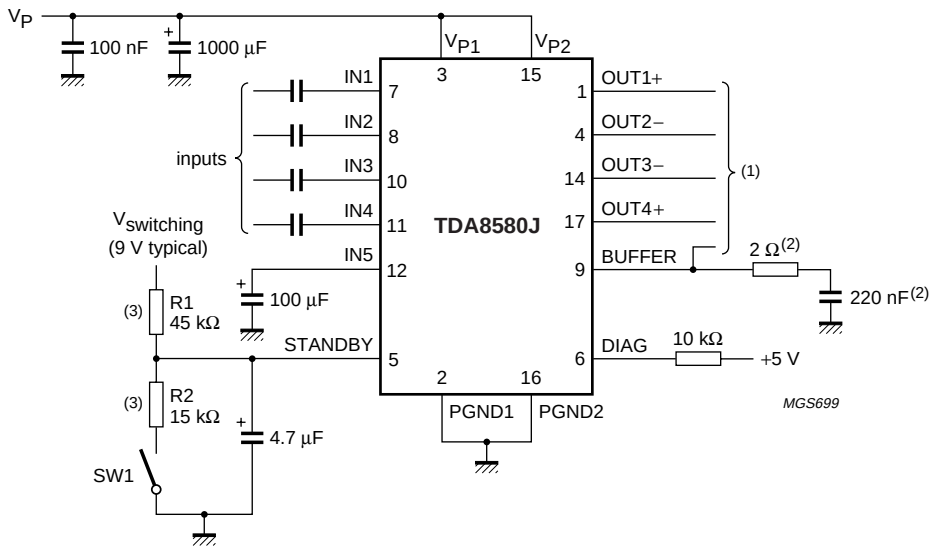
(1) R1 and R2 values depend on $V_{switching}$ applied; the value of R1 and R2 connected in parallel should be minimum 10 kΩ.

Fig.29 Quad single-ended application; $V_P \leq 18$ V.



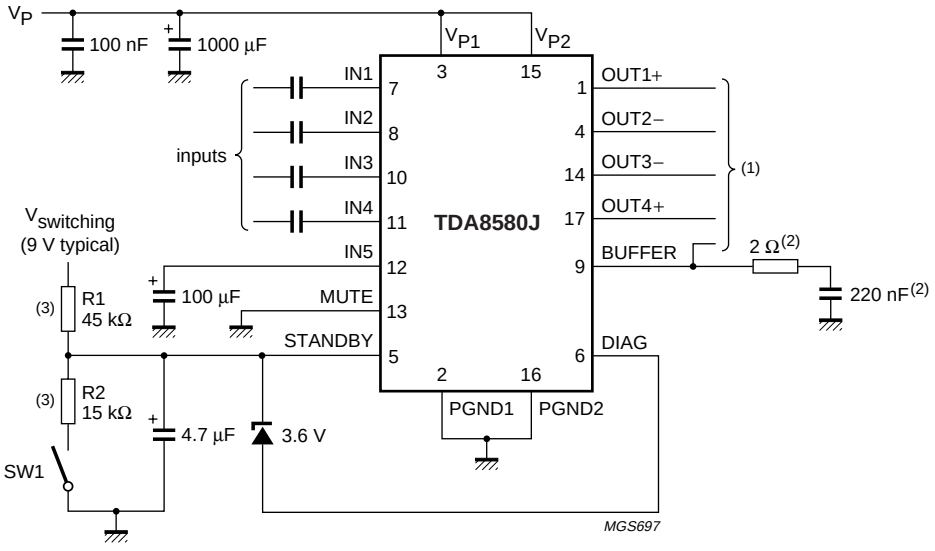
(1) R1 and R2 values depend on $V_{switching}$ applied; the value of R1 and R2 connected in parallel should be minimum 10 kΩ.

Fig.30 Dual single-ended and one bridge-tied load application; $V_P \leq 18$ V.



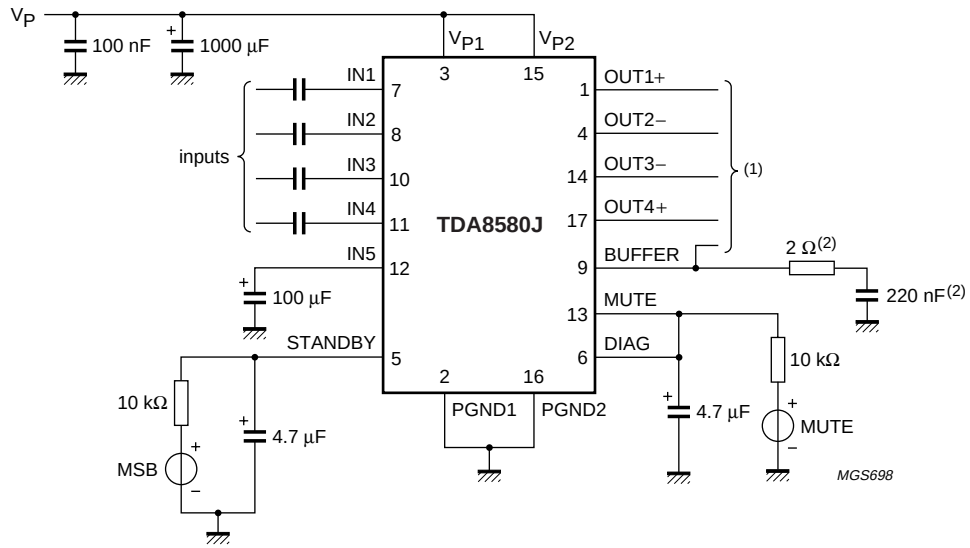
(1) Load conditions: quad SE (4 x 4 Ω), or dual BTL (2 x 8 Ω), or dual SE (2 x 4 Ω) and one BTL (1 x 8 Ω).
(2) RC combination not required in BTL mode.
(3) R1 and R2 values depend on $V_{switching}$ applied; the value of R1 and R2 connected in parallel should be minimum 10 kΩ.

Fig.31 Application 1; supply voltage range 8 V < V_P ≤ 18 V; 1-pin and 2-pin operation.



(1) Load conditions: quad SE (4 x 4 Ω), or dual BTL (2 x 8 Ω), or dual SE (2 x 4 Ω) and one BTL (1 x 8 Ω).
(2) RC combination not required in BTL mode.
(3) R1 and R2 values depend on $V_{switching}$ applied; the value of R1 and R2 connected in parallel should be minimum 10 kΩ.

Fig.32 Application 2; supply voltage range 18 V < V_P ≤ 24 V; 1-pin operation.

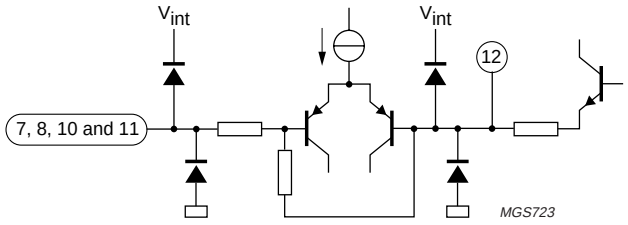
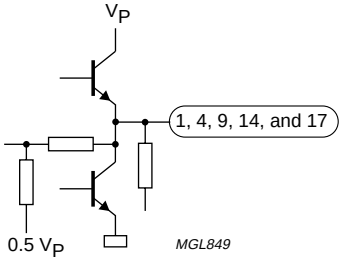


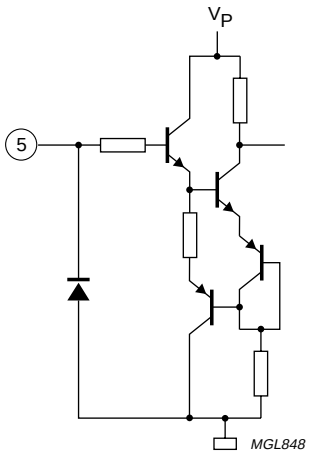
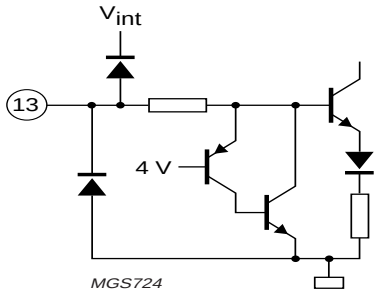
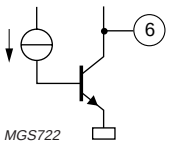
(1) Load conditions: quad SE (4 x 4 Ω), or dual BTL (2 x 8 Ω), or dual SE (2 x 4 Ω) and one BTL (1 x 8 Ω)

(2) RC combination not required in BTL mode.

Fig.33 Application 3; supply voltage range 18 V < V_P ≤ 24 V; 2-pin operation.

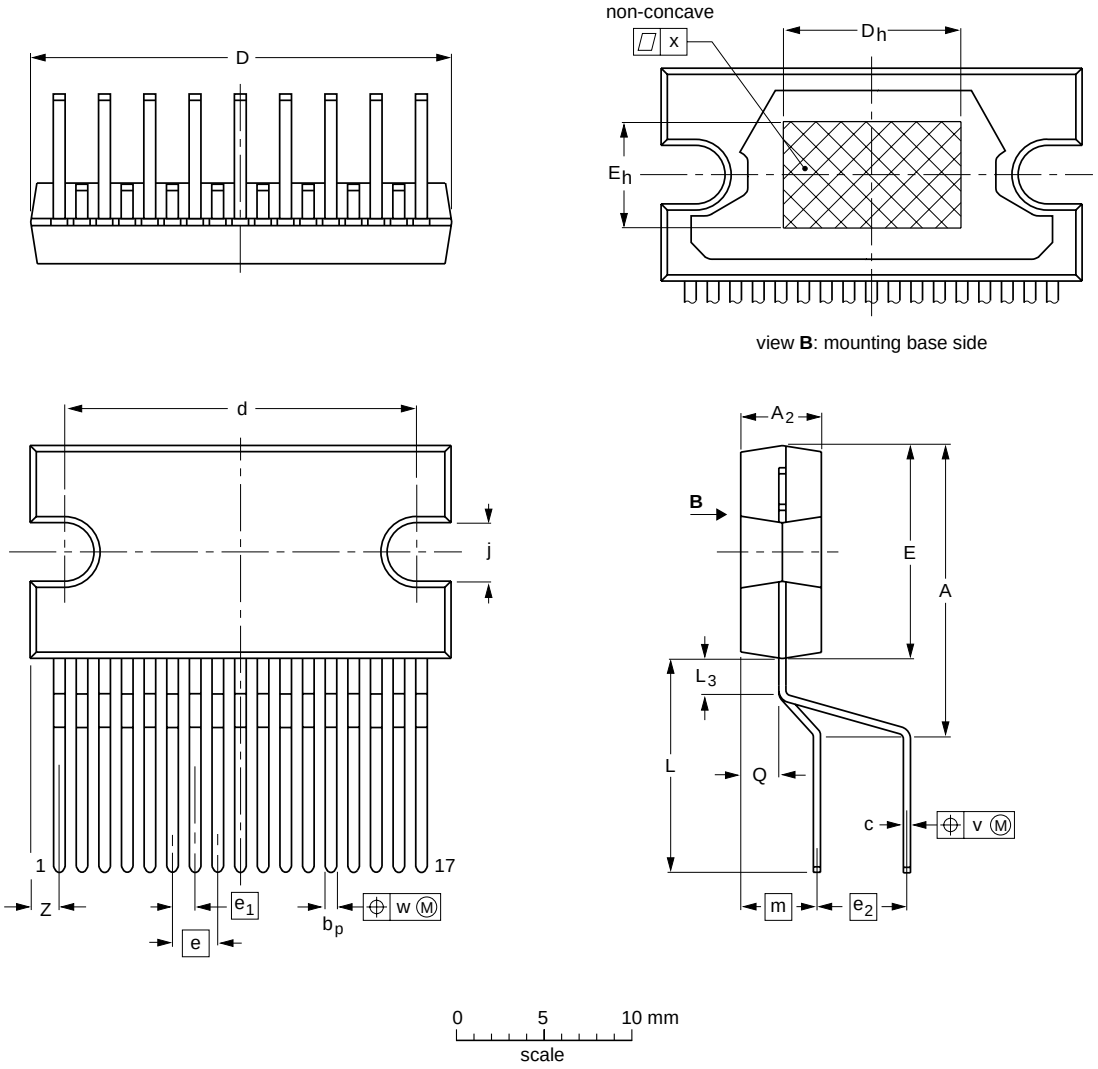
INTERNAL PIN CONFIGURATION

PIN	NAME	EQUIVALENT CIRCUIT
7, 8, 10, 11 and 12	Inputs	
1, 4, 9, 14 and 17	Outputs	

PIN	NAME	EQUIVALENT CIRCUIT
5	STANDBY	
13	MUTE	
6	DIAG	

PACKAGE OUTLINE

DBS17P: plastic DIL-bent-SIL power package; 17 leads (lead length 12 mm) **SOT243-1**



DIMENSIONS (mm are the original dimensions)

UNIT	A	A_2	b_p	c	$D^{(1)}$	d	D_h	$E^{(1)}$	e	e_1	e_2	E_h	j	L	L_3	m	Q	v	w	x	$Z^{(1)}$
mm	17.0 15.5	4.6 4.4	0.75 0.60	0.48 0.38	24.0 23.6	20.0 19.6	10	12.2 11.8	2.54	1.27	5.08	6	3.4 3.1	12.4 11.0	2.4 1.6	4.3	2.1 1.8	0.8	0.4	0.03	2.00 1.45

Note

1. Plastic or metal protrusions of 0.25 mm maximum per side are not included.

OUTLINE VERSION	REFERENCES				EUROPEAN PROJECTION	ISSUE DATE
	IEC	JEDEC	EIAJ			
SOT243-1						~~97-12-16~~ 99-12-17

SOLDERING

Introduction to soldering through-hole mount packages

This text gives a brief insight to wave, dip and manual soldering. A more in-depth account of soldering ICs can be found in our *"Data Handbook IC26; Integrated Circuit Packages"* (document order number 9398 652 90011).

Wave soldering is the preferred method for mounting of through-hole mount IC packages on a printed-circuit board.

Soldering by dipping or by solder wave

The maximum permissible temperature of the solder is 260 °C; solder at this temperature must not be in contact with the joints for more than 5 seconds.

The total contact time of successive solder waves must not exceed 5 seconds.

The device may be mounted up to the seating plane, but the temperature of the plastic body must not exceed the specified maximum storage temperature ($T_{stg(max)}$). If the printed-circuit board has been pre-heated, forced cooling may be necessary immediately after soldering to keep the temperature within the permissible limit.

Manual soldering

Apply the soldering iron (24 V or less) to the lead(s) of the package, either below the seating plane or not more than 2 mm above it. If the temperature of the soldering iron bit is less than 300 °C it may remain in contact for up to 10 seconds. If the bit temperature is between 300 and 400 °C, contact may be up to 5 seconds.

Suitability of through-hole mount IC packages for dipping and wave soldering methods

PACKAGE	SOLDERING METHOD	
	DIPPING	WAVE
DBS, DIP, HDIP, SDIP, SIL	suitable	suitable[1]

Note

1. For SDIP packages, the longitudinal axis must be parallel to the transport direction of the printed-circuit board.

DATA SHEET STATUS

DATA SHEET STATUS	PRODUCT STATUS	DEFINITIONS [1]
Objective specification	Development	This data sheet contains the design target or goal specifications for product development. Specification may change in any manner without notice.
Preliminary specification	Qualification	This data sheet contains preliminary data, and supplementary data will be published at a later date. Philips Semiconductors reserves the right to make changes at any time without notice in order to improve design and supply the best possible product.
Product specification	Production	This data sheet contains final specifications. Philips Semiconductors reserves the right to make changes at any time without notice in order to improve design and supply the best possible product.

Note

1. Please consult the most recently issued data sheet before initiating or completing a design.

DEFINITIONS

Short-form specification — The data in a short-form specification is extracted from a full data sheet with the same type number and title. For detailed information see the relevant data sheet or data handbook.

Limiting values definition — Limiting values given are in accordance with the Absolute Maximum Rating System (IEC 60134). Stress above one or more of the limiting values may cause permanent damage to the device. These are stress ratings only and operation of the device at these or at any other conditions above those given in the Characteristics sections of the specification is not implied. Exposure to limiting values for extended periods may affect device reliability.

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